

# PREFERENCE-BASED BATCH AND SEQUENTIAL TEACHING: TOWARDS A UNIFIED VIEW OF MODELS

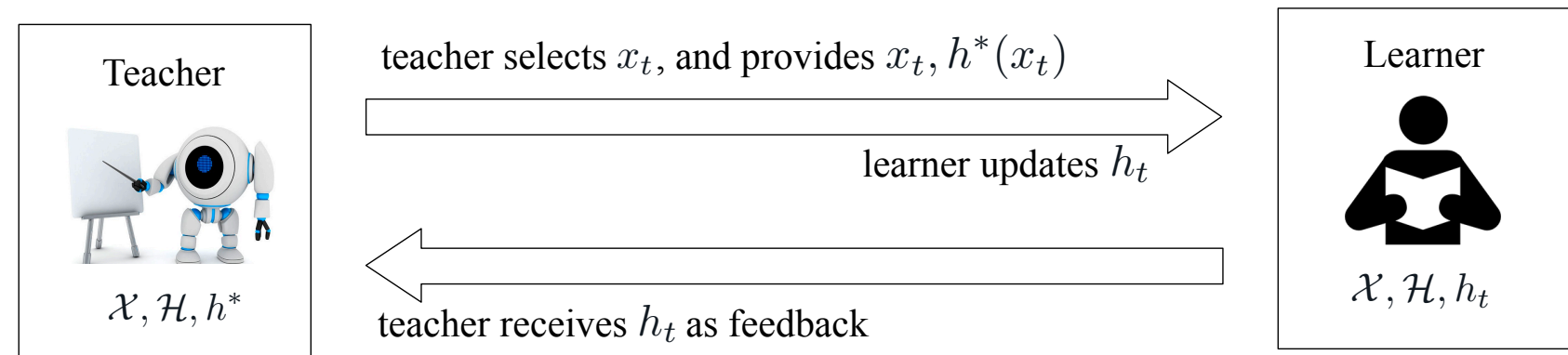
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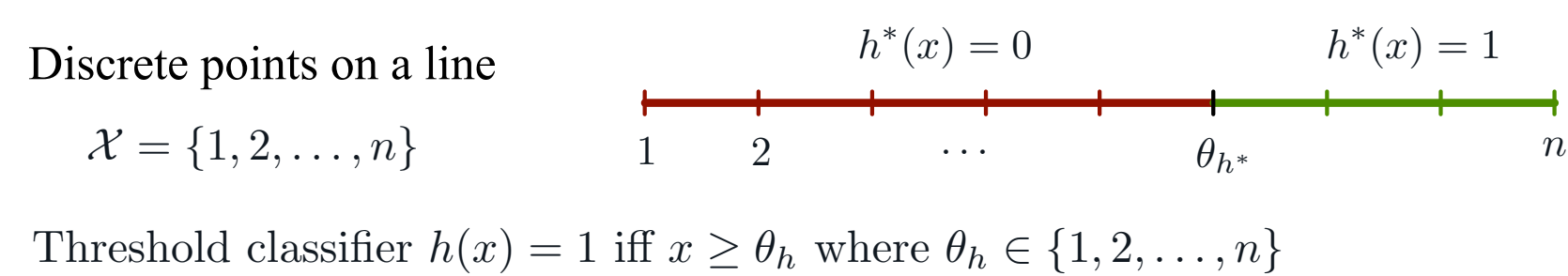
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## Algorithmic Teaching



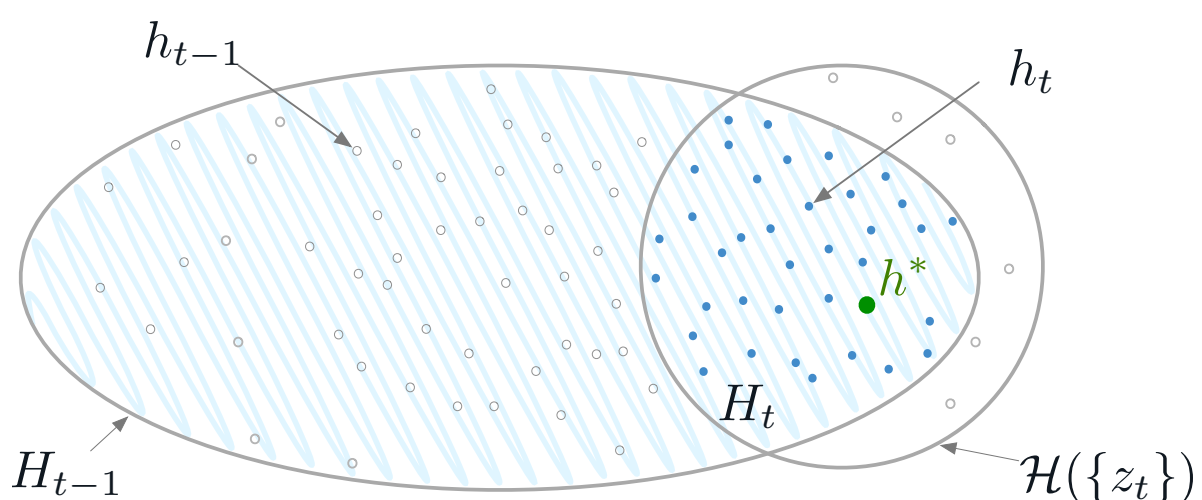
### Canonical Example



Complexity of passive learning:  $O(n)$ ; active learning:  $O(\log(n))$ ; teaching: 2.

### Interaction Protocol

- 1: learner's initial version space is  $H_0 = \mathcal{H}$  and learner starts from  $h_0 \in \mathcal{H}$
- 2: **for**  $t = 1, 2, 3, \dots$  **do**
- 3:    teacher provides  $z_t = (x_t, h^*(x_t))$
- 4:    learner updates  $H_t = H_{t-1} \cap \mathcal{H}(\{z_t\})$ ; picks  $h_t \in H_t$
- 5:    teacher receives  $h_t$  as feedback from the learner
- 6:    **if**  $h_t = h^*$  **then**    teaching process terminates



## Complexity Measures

| Notions    | Description                                             |
|------------|---------------------------------------------------------|
| TD         | classical worst-case teaching complexity                |
| RTD        | notion of TD when teaching a collaborative learner      |
| NCTD       | strongest notion of TD that respects collusion-freeness |
| Local-PBTD | teaching complexity of a weak sequential model          |

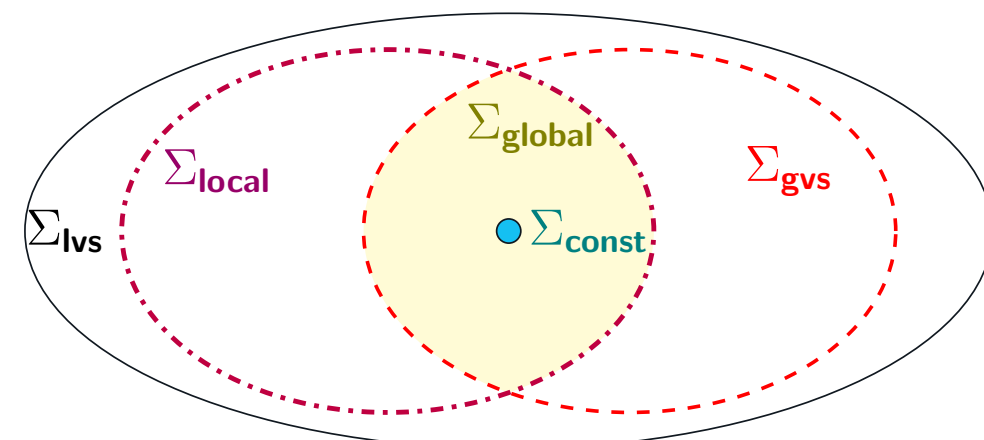
## Research Questions

- Is there a framework unifying different notions of TD's?
- Can we identify models with teaching complexity linear in the Vapnik–Chervonenkis dimension VCD?

## Our Contributions

A novel framework capturing the teaching process via preference functions  $\Sigma$ , where each function  $\sigma \in \Sigma$  induces a teacher-learner pair. Our main results are as follows:

- We show that existing batch models correspond to specific families of  $\sigma$  functions in our framework.
- We identify sequential models with teaching complexity linear in the VCD of the hypothesis class.
- We provide a constructive procedure to find  $\sigma$  functions with low teaching complexity.



**Table 1: Main Results**

| Families           | $\Sigma_{\text{const}}$ | $\Sigma_{\text{global}}$ | $\Sigma_{\text{gvs}}$ | $\Sigma_{\text{local}}$ | $\Sigma_{\text{lvs}}$ |
|--------------------|-------------------------|--------------------------|-----------------------|-------------------------|-----------------------|
| Reduction          | TD                      | RTD                      | NCTD                  | Local-PBTD              | –                     |
| Complexity Results | –                       | $O(\text{VCD}^2)$        | $O(\text{VCD}^2)$     | $O(\text{VCD}^2)$       | $O(\text{VCD})$       |
|                    | [GK95]                  | [Zil+11]                 | [KSZ19]               | [Che+18]                | –                     |

## Learner's Preference Function

A preference function  $\sigma : \mathcal{H} \times 2^{\mathcal{H}} \times \mathcal{H} \rightarrow \mathbb{R}$  models how a learner navigates in the version space as it receives teaching examples (*line 4 of Interaction Protocol*):

$$h_t \in \arg \min_{h' \in H_t} \sigma(h'; H_t, h_{t-1}).$$

## Teaching Complexity $\Sigma$ -TD

### Teaching Dimension for a Preference Function

Fix  $\mathcal{X}$ ,  $\mathcal{H}$ , and learner's initial hypothesis  $h_0$ . Let  $D_{\mathcal{X}, \mathcal{H}, h_0}(\sigma, h^*)$  be the worst-case optimal cost for steering the learner from  $h_0$  to  $h^*$  for some preference function  $\sigma$ . Then, the teaching dimension w.r.t.  $\sigma$  is defined as the worst-case optimal cost for teaching any target  $h^*$ :

$$\text{TD}_{\mathcal{X}, \mathcal{H}, h_0}(\sigma) = \max_{h^*} D_{\mathcal{X}, \mathcal{H}, h_0}(\sigma, h^*).$$

### Teaching Dimension for a Family of Preference Functions

We define the teaching dimension for a family  $\Sigma$  as the teaching dimension w.r.t. the best  $\sigma \in \Sigma$ :

$$\Sigma\text{-TD}_{\mathcal{X}, \mathcal{H}, h_0} = \min_{\sigma \in \Sigma} \text{TD}_{\mathcal{X}, \mathcal{H}, h_0}(\sigma).$$

### Collusion-free Preference Functions

**Definition 1 (Collusion-free teaching [GM96] (batch setting))** *A learner outputting hypothesis  $h$  will not change its output if given additional information consistent with  $h$ .*

**Definition 2 (Collusion-free preference (this paper))** *If  $h$  is the only hypothesis in the most preferred set defined by  $\sigma$ , then the learner will stay at  $h$  if additional information received by the learner is consistent with  $h$ .*

We study preference functions that are collusion-free as per Definition 2:

$$\Sigma_{\text{CF}} = \{\sigma \mid \sigma \text{ is collusion-free}\}.$$

## Preference-based Teaching Models

- Batch models:

- $\Sigma_{\text{const}} = \{\sigma \in \Sigma_{\text{CF}} \mid \exists c \in \mathbb{R}, \text{ s.t. } \forall h', H, h, \sigma(h'; H, h) = c\}$
- $\Sigma_{\text{global}} = \{\sigma \in \Sigma_{\text{CF}} \mid \exists g : \mathcal{H} \rightarrow \mathbb{R}, \text{ s.t. } \forall h', H, h, \sigma(h'; H, h) = g(h')\}$
- $\Sigma_{\text{gvs}} = \{\sigma \in \Sigma_{\text{CF}} \mid \exists g : \mathcal{H} \times 2^{\mathcal{H}} \rightarrow \mathbb{R}, \text{ s.t. } \forall h', H, h, \sigma(h'; H, h) = g(h', H)\}$

- Sequential models:

- $\Sigma_{\text{local}} = \{\sigma \in \Sigma_{\text{CF}} \mid \exists g : \mathcal{H} \times \mathcal{H} \rightarrow \mathbb{R}, \text{ s.t. } \forall h', H, h, \sigma(h'; H, h) = g(h', h)\}$
- $\Sigma_{\text{lvs}} = \{\sigma \in \Sigma_{\text{CF}} \mid \exists g : \mathcal{H} \times 2^{\mathcal{H}} \times \mathcal{H} \rightarrow \mathbb{R}, \text{ s.t. } \forall h', H, h, \sigma(h'; H, h) = g(h', H, h)\}$

- Teaching sequences with different preference functions for the Warmuth hypothesis class:

| $h \backslash x$ | $x_1$ | $x_2$ | $x_3$ | $x_4$ | $x_5$ | $\mathcal{S}_{\text{const}} = \mathcal{S}_{\text{global}}$ | $\mathcal{S}_{\text{gvs}}$ | $\mathcal{S}_{\text{local}}$ | $\mathcal{S}_{\text{lvs}}$ |
|------------------|-------|-------|-------|-------|-------|------------------------------------------------------------|----------------------------|------------------------------|----------------------------|
| $h_1$            | 1     | 1     | 0     | 0     | 0     | $(x_1, x_2, x_4)$                                          | $(x_1, x_2)$               | $(x_1)$                      | $(x_1)$                    |
| $h_2$            | 0     | 1     | 1     | 0     | 0     | $(x_2, x_3, x_5)$                                          | $(x_2, x_3)$               | $(x_3)$                      | $(x_2)$                    |
| $h_3$            | 0     | 0     | 1     | 1     | 0     | $(x_1, x_3, x_4)$                                          | $(x_3, x_4)$               | $(x_3, x_4)$                 | $(x_3)$                    |
| $h_4$            | 0     | 0     | 0     | 1     | 1     | $(x_2, x_4, x_5)$                                          | $(x_4, x_5)$               | $(x_5, x_4)$                 | $(x_4)$                    |
| $h_5$            | 1     | 0     | 0     | 0     | 1     | $(x_1, x_3, x_5)$                                          | $(x_1, x_5)$               | $(x_5)$                      | $(x_5)$                    |
| $h_6$            | 1     | 1     | 0     | 1     | 0     | $(x_1, x_2, x_4)$                                          | $(x_2, x_4)$               | $(x_4)$                      | $(x_3)$                    |
| $h_7$            | 0     | 1     | 1     | 0     | 1     | $(x_2, x_3, x_5)$                                          | $(x_3, x_5)$               | $(x_3, x_5)$                 | $(x_4)$                    |
| $h_8$            | 1     | 0     | 1     | 1     | 0     | $(x_1, x_3, x_4)$                                          | $(x_1, x_4)$               | $(x_4, x_3)$                 | $(x_5)$                    |
| $h_9$            | 0     | 1     | 0     | 1     | 1     | $(x_2, x_4, x_5)$                                          | $(x_4, x_5)$               | $(x_4, x_5)$                 | $(x_1)$                    |
| $h_{10}$         | 1     | 0     | 1     | 0     | 1     | $(x_1, x_3, x_5)$                                          | $(x_1, x_3)$               | $(x_5, x_3)$                 | $(x_2)$                    |

(a) The Warmuth hypothesis class and the corresponding teaching sequences (denoted by  $\mathcal{S}$ ).

| $h' \backslash h$                          | $\forall h' \in H$ | $h \backslash h'$                           | $h_1$ | $h_2$ | $h_3$ | $h_4$ | $h_5$ | $h_6$ | $h_7$ | $h_8$ | $h_9$ | $h_{10}$ |
|--------------------------------------------|--------------------|---------------------------------------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|----------|
| $\sigma_{\text{const}}(h'; \cdot, \cdot)$  | $\forall h' \in H$ | $\sigma_{\text{local}}(h'; \cdot, h = h_1)$ | 0     | 2     | 4     | 4     | 2     | 1     | 3     | 3     | 3     | 3        |
| $\sigma_{\text{global}}(h'; \cdot, \cdot)$ |                    |                                             |       |       |       |       |       |       |       |       |       |          |

(b)  $\sigma_{\text{const}}$  and  $\sigma_{\text{global}}$

(c)  $\sigma_{\text{local}}$  representing the Hamming distance between  $h'$  and  $h$ .

### Main Results

- Reduction to existing notions of TD's (see Table 1).
- Proving  $\Sigma_{\text{lvs}}\text{-TD}_{\mathcal{X}, \mathcal{H}, h_0} = O(\text{VCD}(\mathcal{H}, \mathcal{X}))$  via a constructive procedure.

### Key Ideas for Constructing $\sigma \in \Sigma_{\text{lvs}}$ with $\text{TD}_{\mathcal{X}, \mathcal{H}, h_0}(\sigma) = O(\text{VCD})$

- Introducing a new notion of *compact distinguishable set*.
- Partitioning the hypothesis class into subsets of hypothesis classes with lower VCD using the compact distinguishable set.
- Recursively applying the partitioning procedure to create the preference function  $\sigma$ .

### Discussions

- Designing  $\sigma$  functions for addressing the open question of whether RTD is linear in VCD.
- Designing teaching algorithms for sequential models.

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